



#### LinFlex and I2S emulation via GTM

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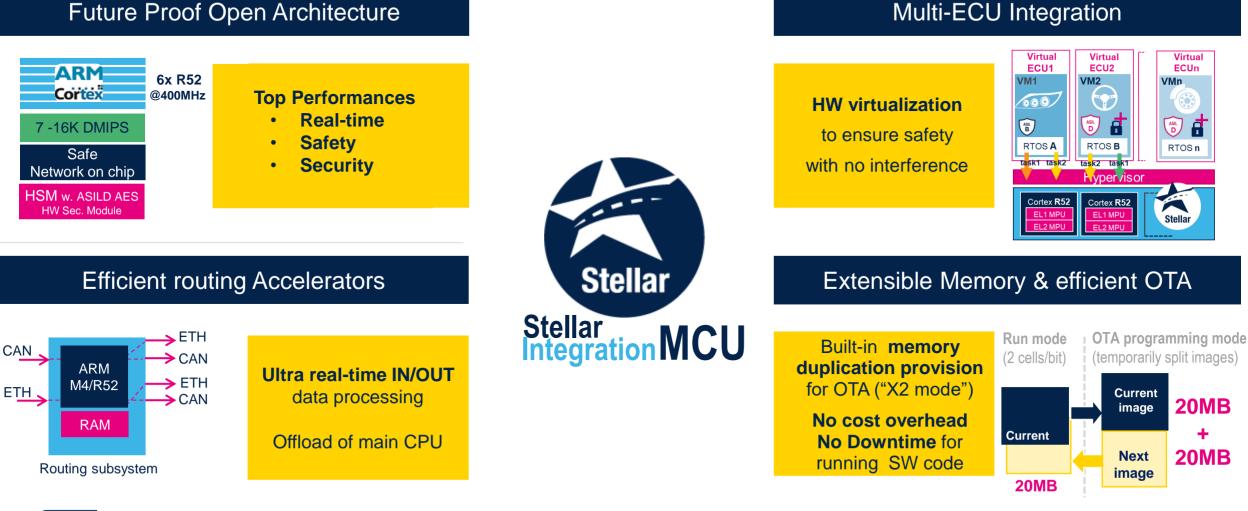
#### Unified computing platform for new vehicle architectures

SOFTWARE-DEFINED VEHICLE Lead transformation towards lean & smart architecture	Stellar Platform		Complete value chain for EVs from integration & control to efficient energy management		
Control & Zone Controller Central Computer Zone Controller Controller	Functions INTEGRATION	Inte	ellar P egration platform tion Control	Domain Controller BMS	ICE/EV Transmission
		Inte	ellar G egration platform teway & Body	Central Gateway Body integration	Zone Controller Domain Controller
Actuators & Sensors	ACTUATION		ellar E alog Performance	Traction Inverter BMS	OBC DC/DC





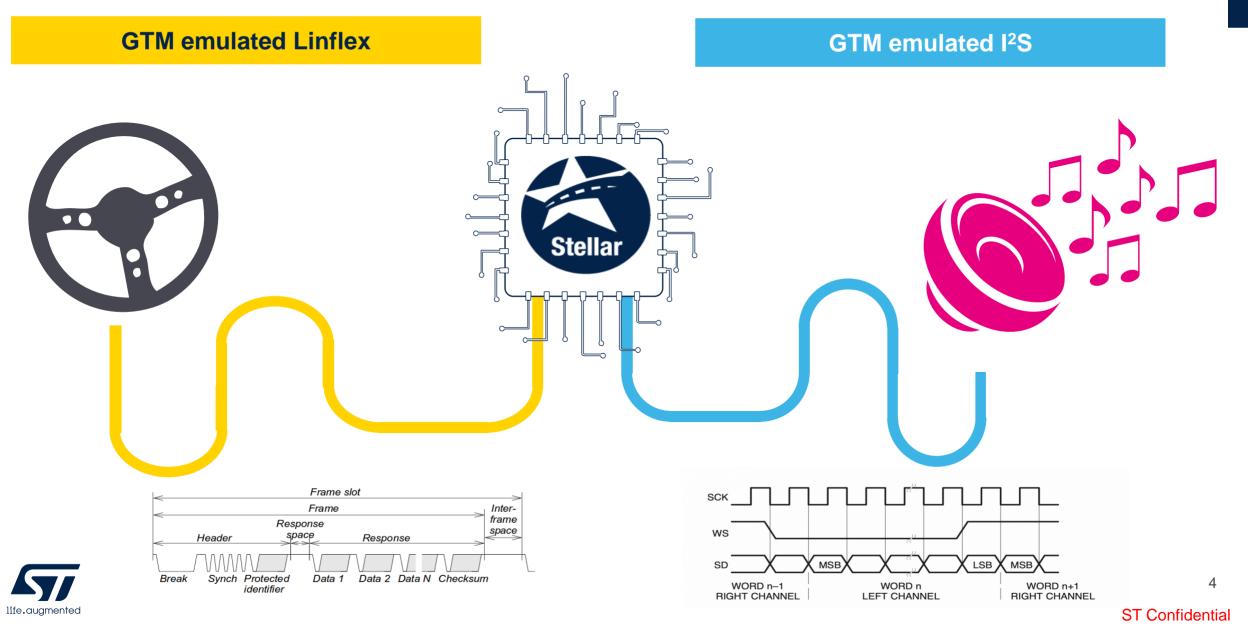
#### **SR6 - Stellar** Integration MCU Innovation with Value



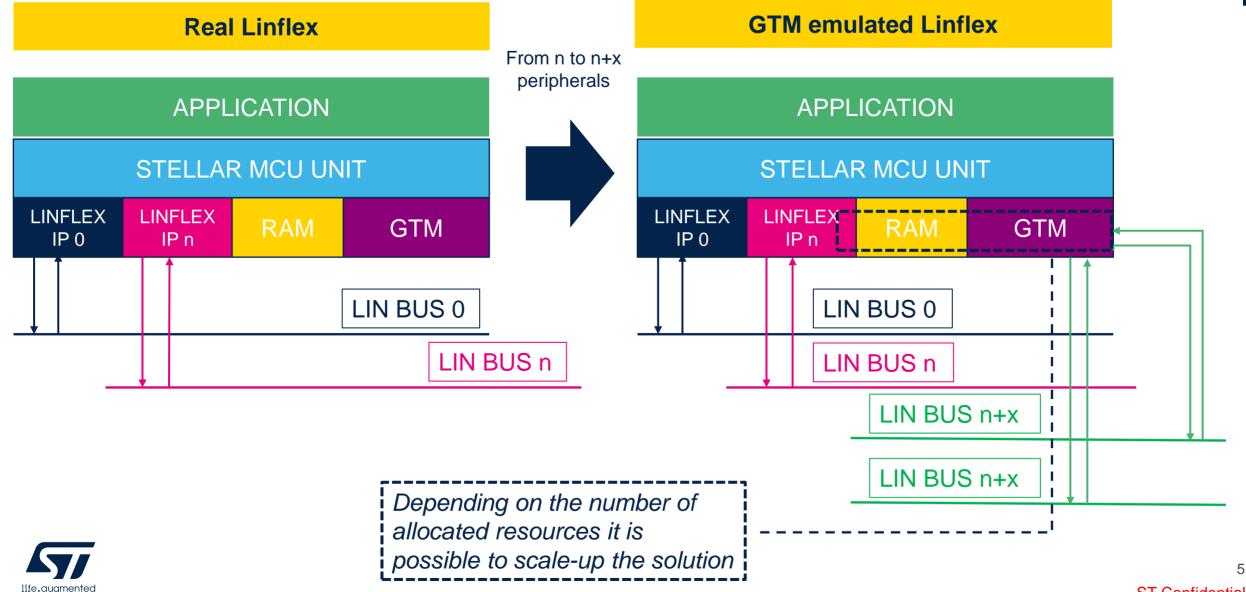
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#### Use cases



## How it works



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## GTM architecture overview

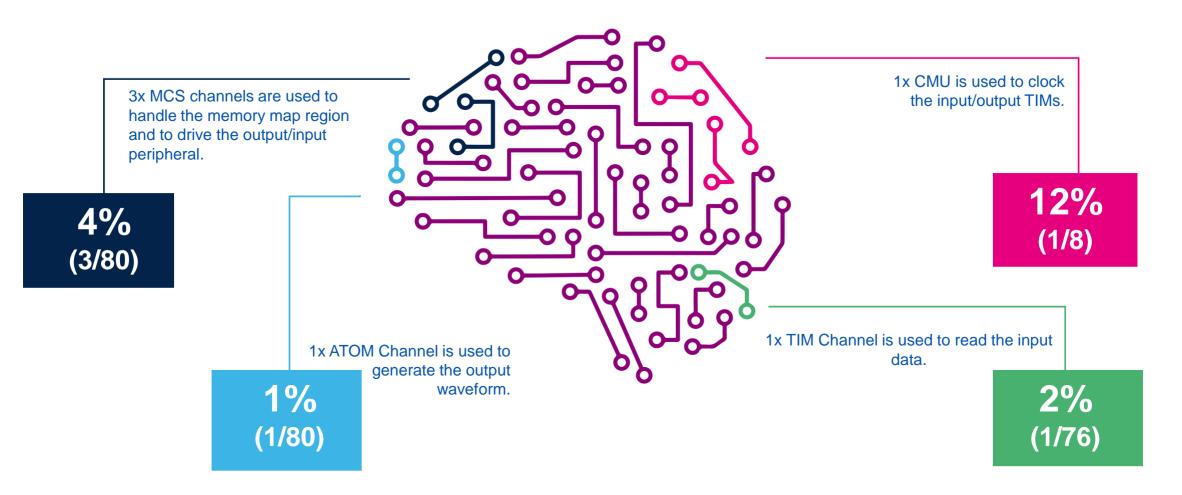
Infrastructure ← ATOM 0,1,2 sub-module **PSM** CMP AEI CMU ICM ← TOM 0.1 (8 ch.) AFD TBU MON FIFO CTBM Output sub-BRC F2A module (x ch.) DPLL Core submodule MAP ATOM0 **Specialized A A** / (8 ch.) sub-module **ARU** ATOMx (8 ch.) SPEy MCS0 MCSx (1 ch.) . . . (8 ch.) (8 ch.) SPE0 (1 ch.) TOM0 TOMy TOMx .... (16 ch.) (16 ch.) (16 ch.)

What is needed?

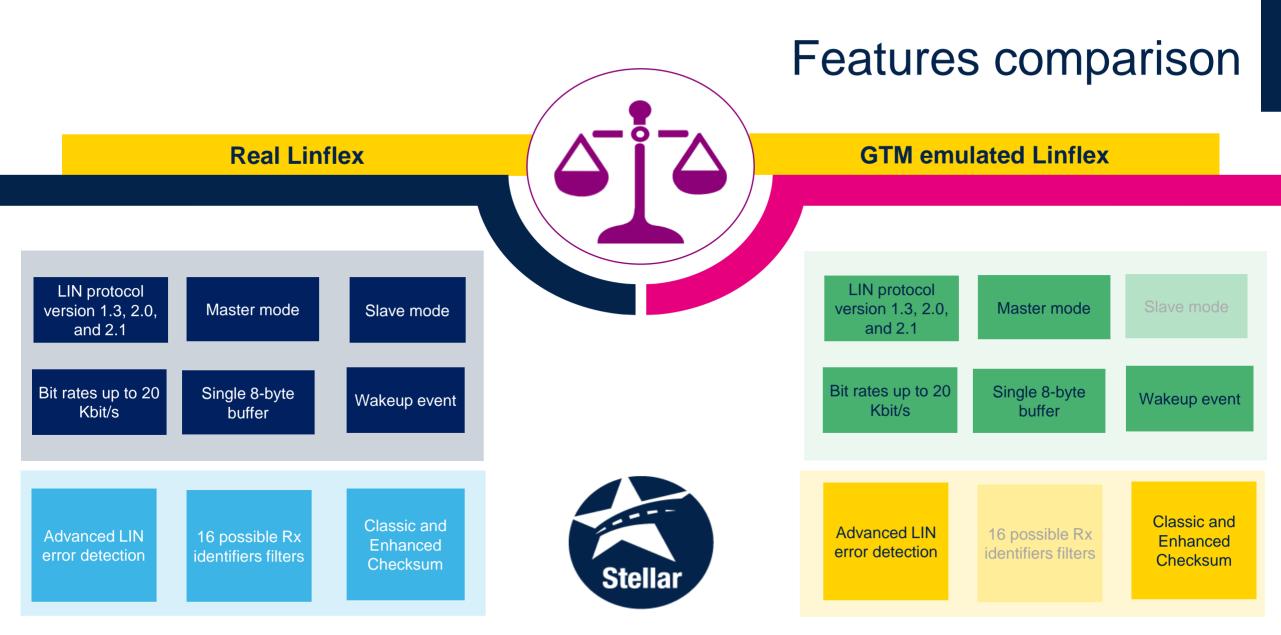
- CMU
- MCS
- ATOM
- TIM
- ARU



## **Emulated Linflex resources**





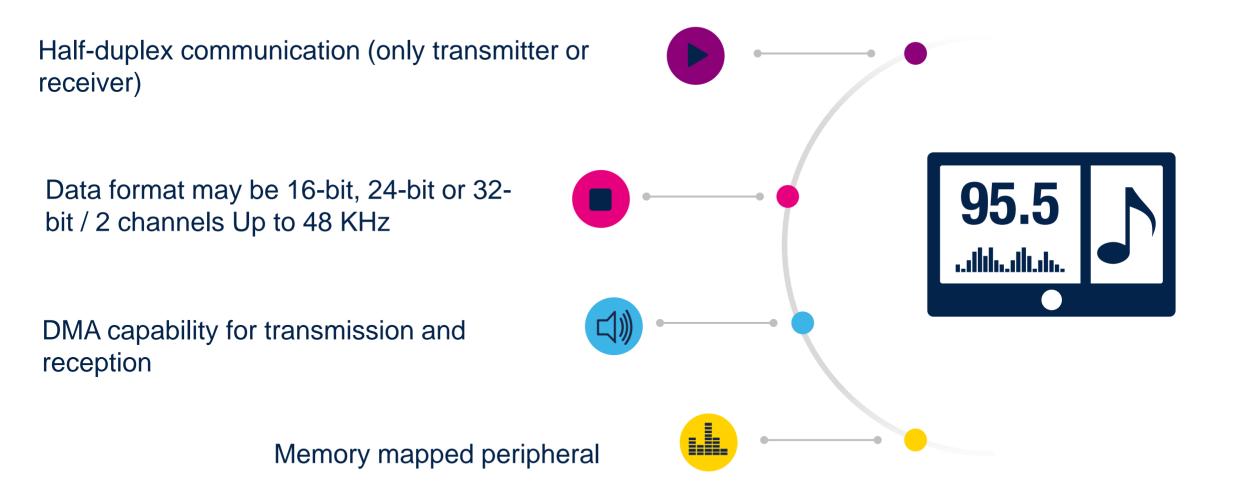




Same features/performance/behaviour as hardware peripheral

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## Digital audio stream (I<sup>2</sup>S)





## Peripherals emulation ecosystem

peripheral interfaces

To increase the freedom of application

PCB layout design phase (Pinout choices)



- HighTec C compiler :
  - Improving readability, reusability & portability

10 idential

#### Conclusions

## ST Stellar and GTM extend connectivity capabilities :

- Possibility to add new peripheral via emulation.
- Possibility to increase the flexibility and configurability.
- No additional CPU load.





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